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Search of small objects by topology matching, context modeling, and pattern mining

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Citation

ZHANG, Wei and NGO, Chong-wah. Search of small objects by topology matching, context modeling, and pattern mining. (2013). *TRECVID 2013 TREC Video Retrieval Evaluation, Gaithersburg, November 20-22*. Available at: https://ink.library.smu.edu.sg/sis_research/6533

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VIREO@INS-TV13

Search of Small Objects by Topology Matching, Context Modeling, and Pattern Mining

Wei Zhang, Chong-Wah Ngo

VIREO: Video REtrieval grOup
City University of Hong Kong

Outlines

- Introduction
- Solutions
 - TC: Topology Checking
 - CM: Context Modeling
 - PM: Pattern Mining
- Conclusion

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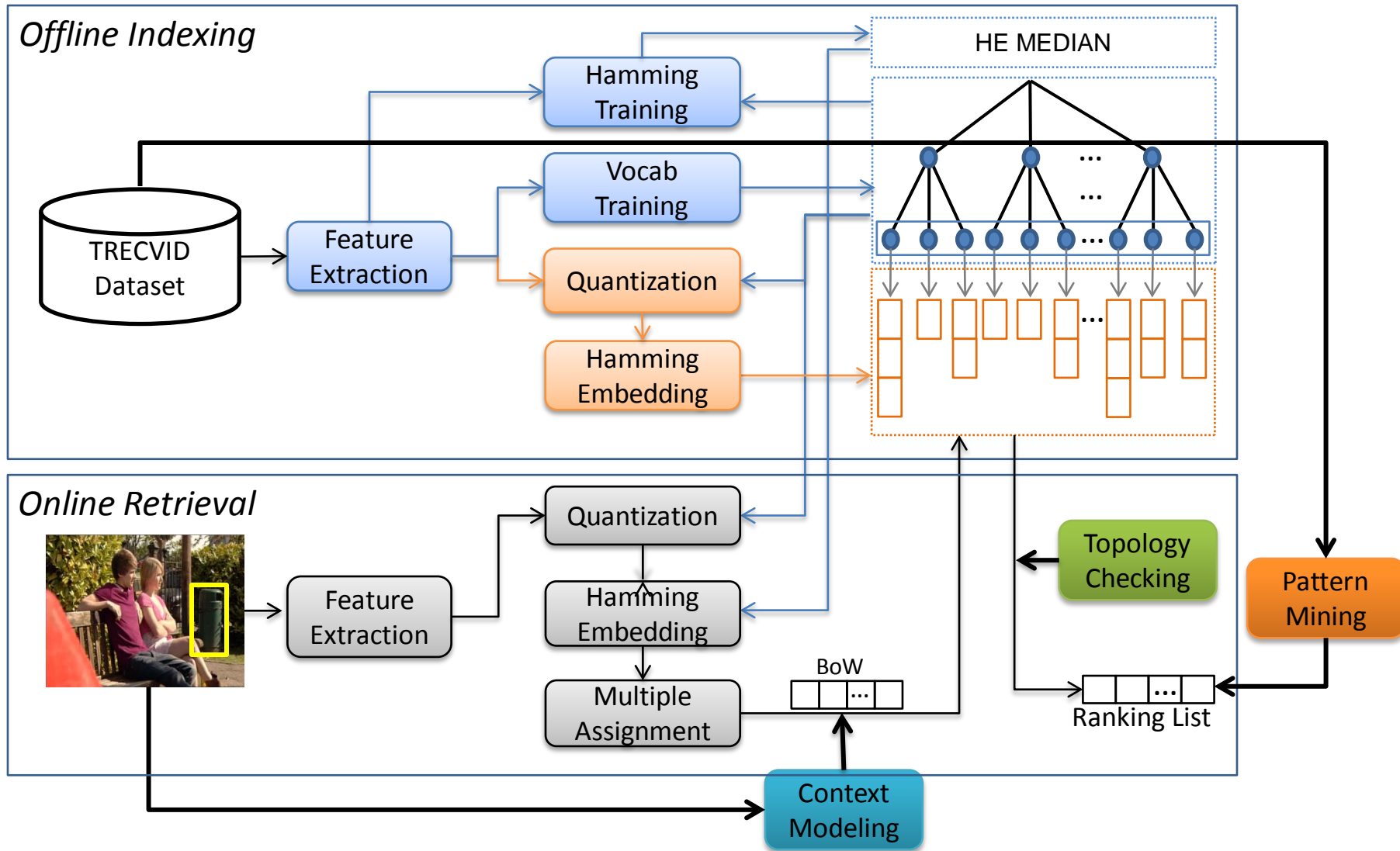
General Information

- Reference dataset
 - 464-hours Videos
 - 470k Shots
 - 640k keyframes
 - 1 frame every 4 seconds
 - ≈ 1.36 frames/shot
- Query
 - 30 topics: object(26) + person(4)
 - query image + ROI
- Our Baseline system
 - BoW model
 - visual matching based on SIFT



9075: a SKOE can

Retrieval Framework

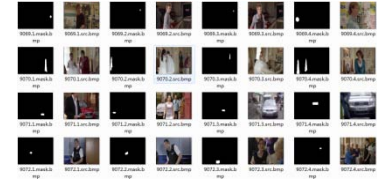


Retrieval Framework

- Time efficiency
 - ~ 300ms/query: time cost for online search
 - ~ 10s/topic, including everything:
 - 4 queries
 - feature extraction, quantization, online search, re-ranking
- Memory cost: ~12 Gbytes
- Source code for the basic framework
 - available as as part of “VIREO-VH: Video Hyperlinking”
 - <http://vireo.cs.cityu.edu.hk/VIREO-VH/>

Main Challenge

- A target is considered as **small**, if it covers **< 10%** area
- For TV13, **77%** of queries are **small** !



small instance on **query** image

- lack of knowledge on the search target

small instance on **reference** image

- similarity score is easily diluted

Topology Checking (TC)

- make better use of limited info by elastic spatial checking

Context Modeling (CM)

- increase information quantity by considering background context

Pattern Mining (PM)

- link small instances offline

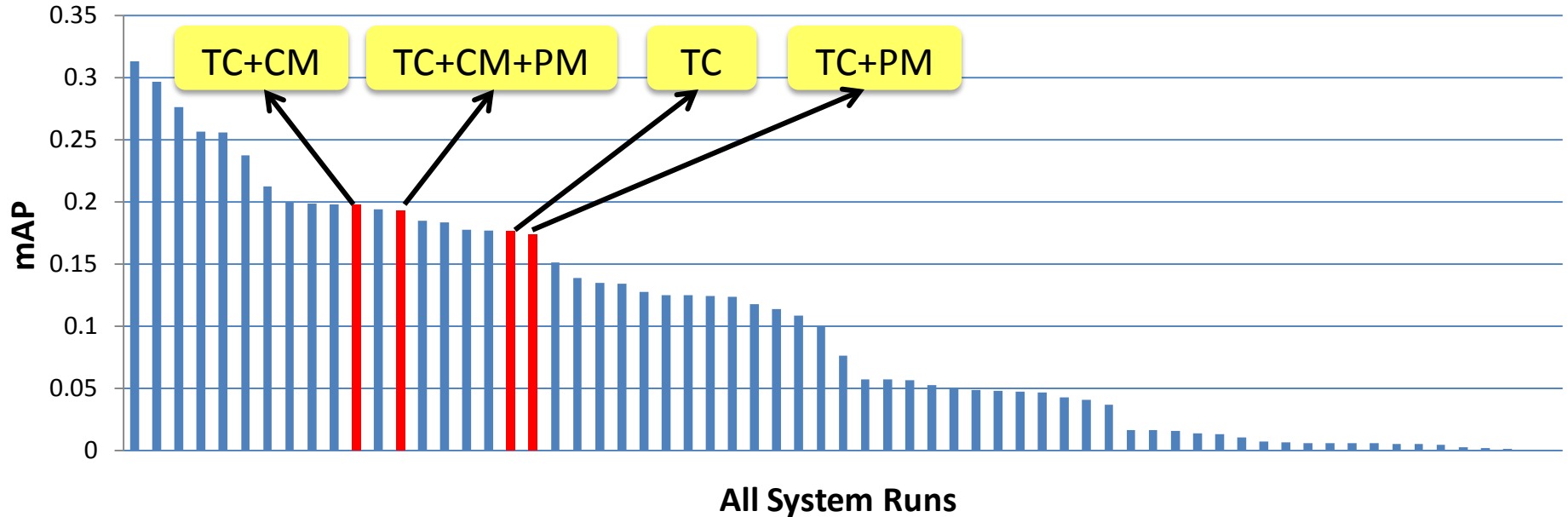
more sparse

$$\downarrow \text{sim}(\mathbf{q}, \mathbf{r}) = \frac{\mathbf{q} \cdot \mathbf{r}}{|\mathbf{q}| |\mathbf{r}|} \uparrow$$

sensitive to noise

Our Submissions

- Three techniques
 - Topology Checking : TC
 - Context Modeling : CM
 - Pattern Mining : PM



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Topology Checking

- Spatial transformation in INS

- What we might expect

- linear transforms (scaling, rotation, translation, shearing)

- What we actual have

- much more complex transforms



- The verification model we want

- tight enough to reject false matches

- tolerant complex spatial transformations



9088: Tamwar – non-rigid motion

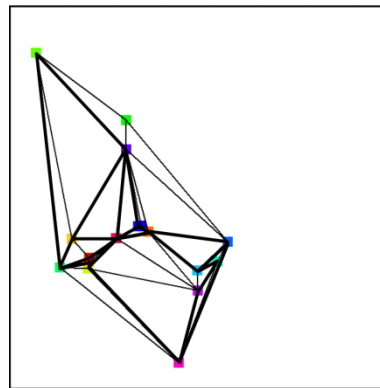
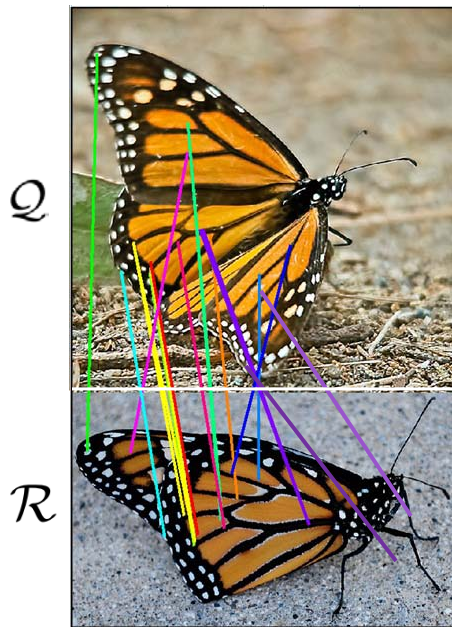


9081: a black taxi – different views of non-planar obj

Topology Checking - Illustration

- Sketch - Match

Delaunay Triangulation (DT)



ΔQ

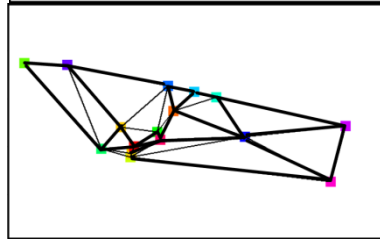
matched points (15)

$\mathbf{E}_{\Delta Q}$: edges in ΔQ

$\mathbf{E}_{\Delta R}$: edges in ΔR

$|\mathbf{E}_{\Delta Q}| = 42$

$|\mathbf{E}_{\Delta R}| = 42$



ΔR

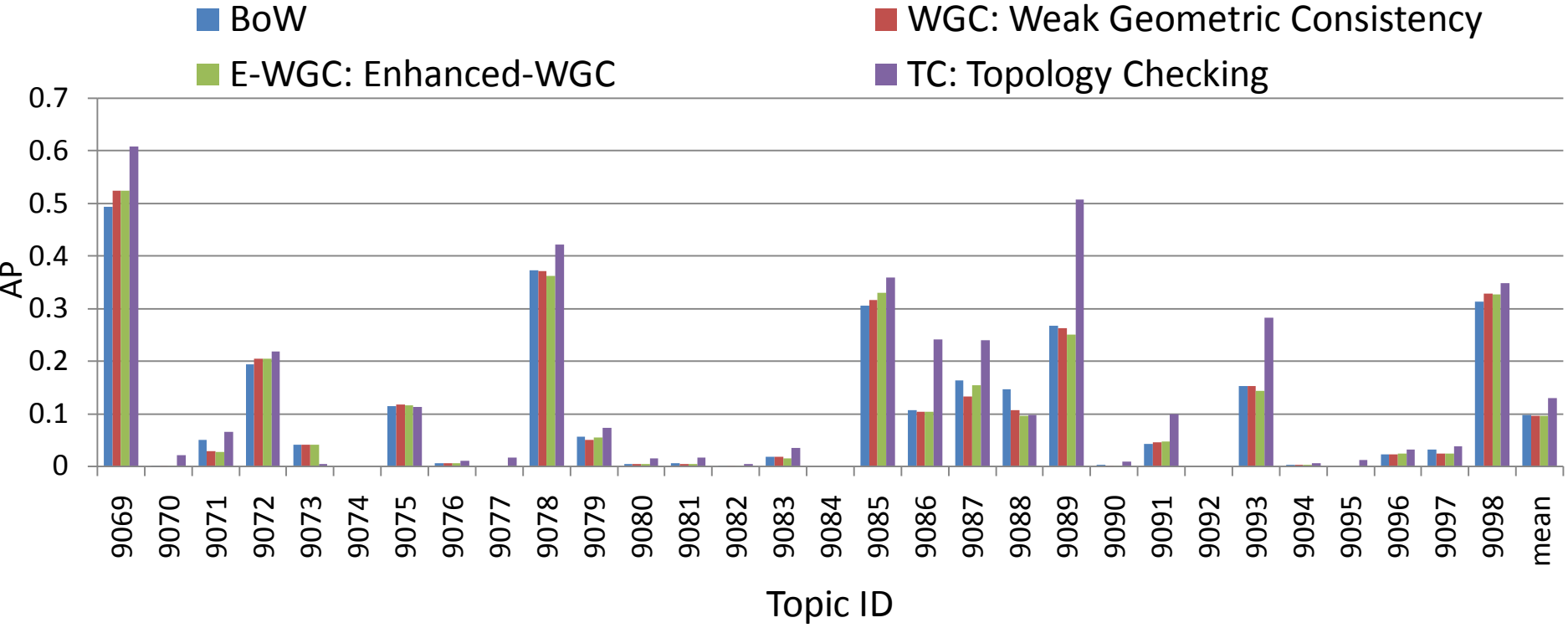
common edges (28)

$$\text{BF}(Q, R) = \|\mathbf{E}_{\Delta Q} \cap \mathbf{E}_{\Delta R}\|$$

Benefits of Topology Checking (TC)

- Edge of the graph
 - encode relative positioning / spatial nearness
- # common edges depicts the topology similarity
- Avoid using noisy local features' scale/orientation
 - local features' orientation / scale are biased
 - only location is used
- Get evidence from multiple local consistent sub-regions
 - robust to small viewpoint change / motion

Results for spatial checking – *ROI Only*



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Full-Image v.s. ROI search

- Full-Image is mostly better, since:
 - limited info inside small ROI
 - high correlation between *ROI* and its *background*
 - they appear/disappear together

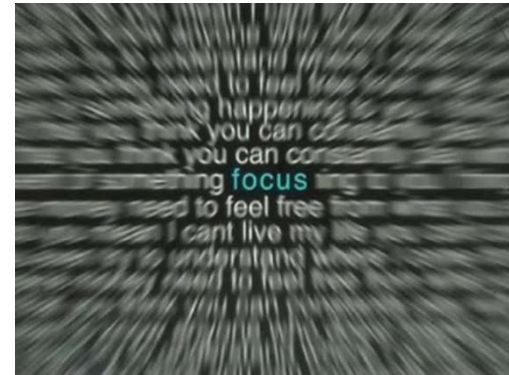


9070: small red obelisk
<obelisk, this painting>
<obelisk, this room>
<obelisk, this woman>

- Sometimes, ROI is better, when:
 - low correlation → instances that could appear anywhere

Context Modeling

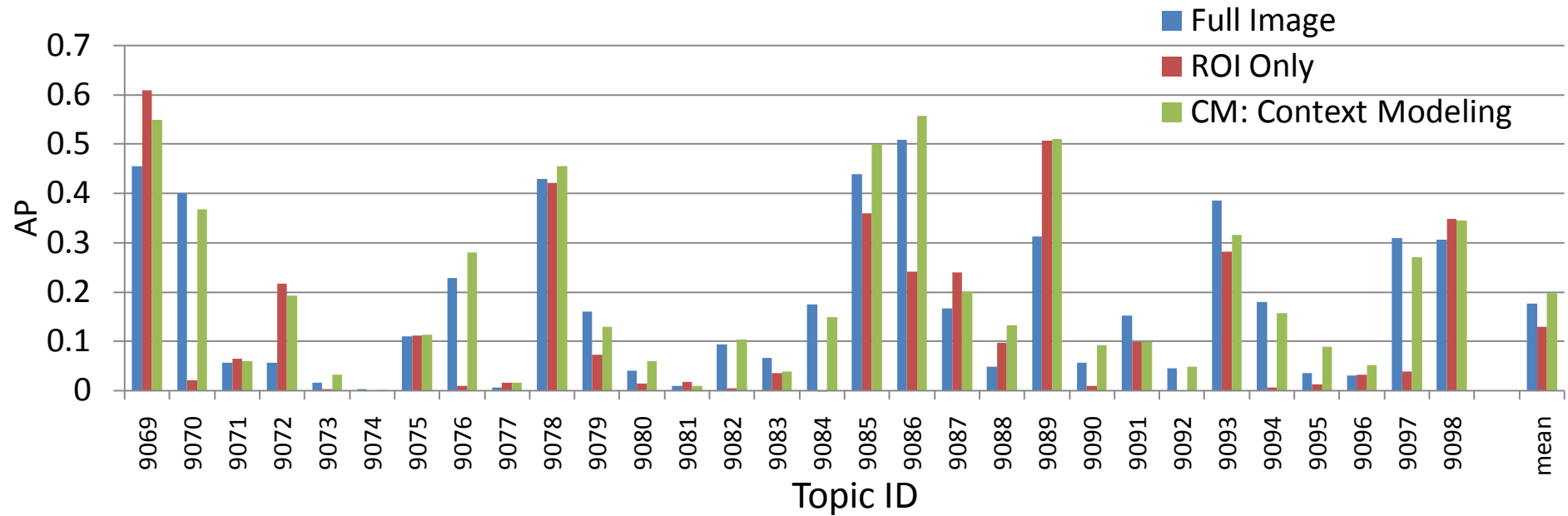
- Observation
 - Feature \in ROI: highly correlated with the target
 - Feature \notin ROI: correlation degenerates quickly.
- Context modeling
 - weight background context
 - simulate the behavior of “stare”
 - blur things away from the focus



$$k(x) = \begin{cases} 1, & \text{if } x \in \mathbf{ROI}, \\ \exp\left(-\frac{\|x-f\|^2}{2\delta^2}\right), & \text{otherwise,} \end{cases} \quad \text{with } \delta^2 = -\frac{\text{diag}^2}{8 \ln 0.1}$$

Results - Context Modeling

- Tradeoff between two extremes
- Avoids zero-performance, when one of them does not work
- Improves overall performance



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Common patterns

- “BBC Easterenders” dataset
 - repetitions of {characters, scenes, objects}
 - hyperlink shots with common patterns

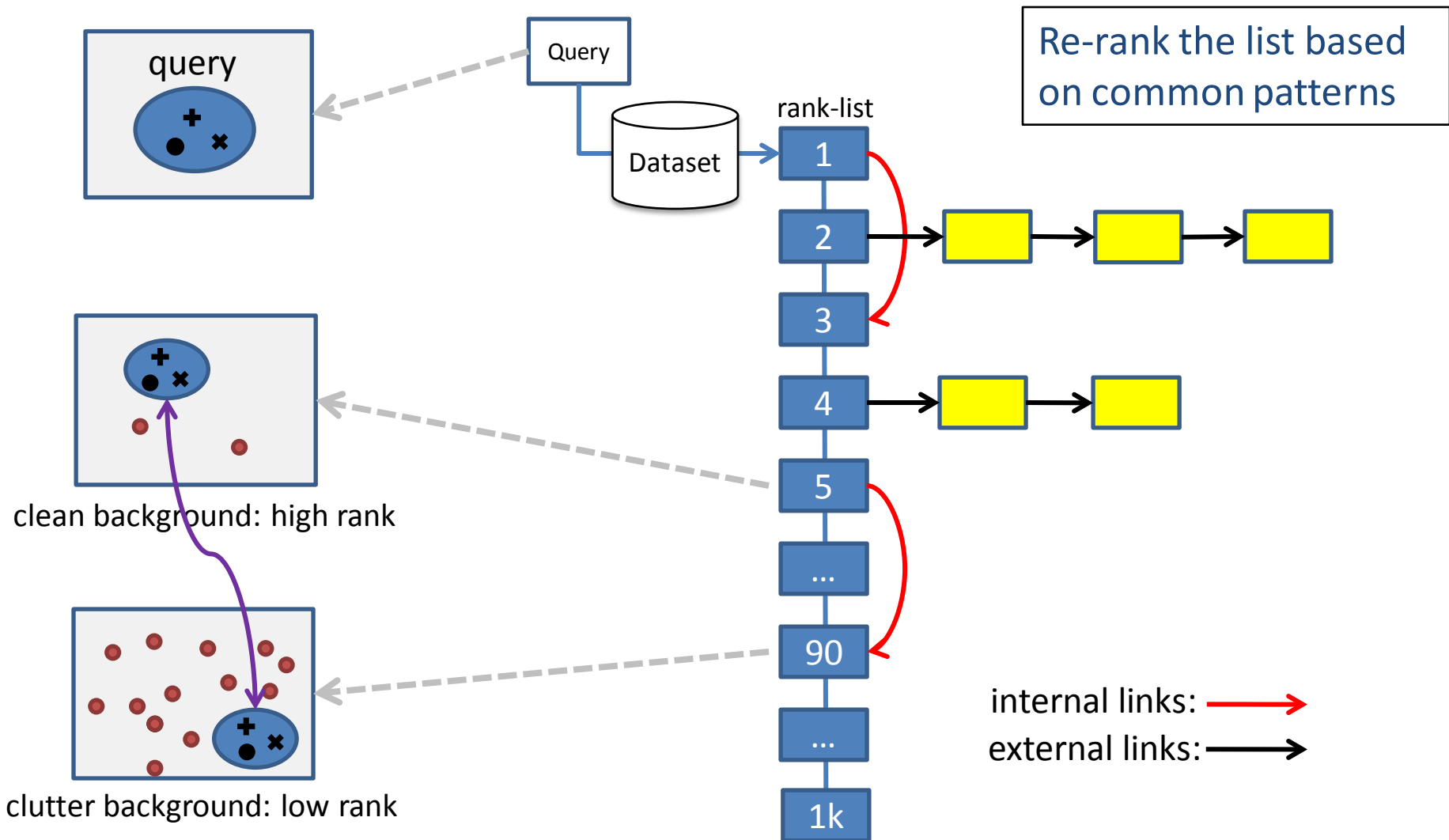


- Are these patterns useful for INS?

- large patterns → no harm
 - Near Duplicates
 - already easy to retrieve
- small patterns → potentially helpful
 - small objects
 - difficult to retrieve

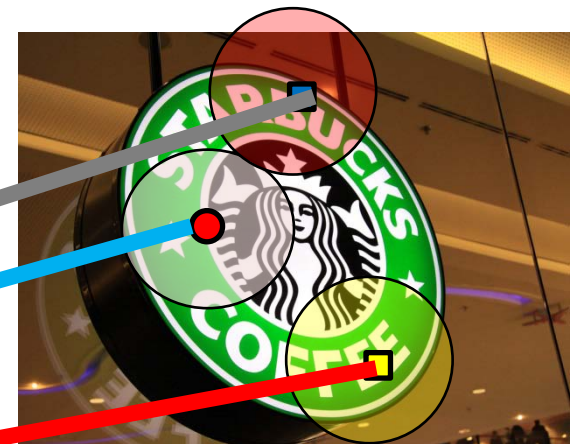
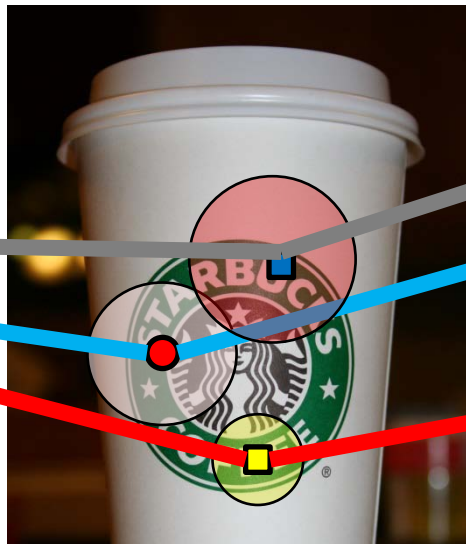


Improve INS with Common Patterns



How to mine Common Patterns

- Extract ToF (Thread of Feature)
 - a ToF is a set of consistent patches across images
 - represented as a set of image ids
- Cluster ToF
 - min-Hash is adopted for efficient clustering
 - clustered ToFs
 - each ToF \rightarrow a link over a set of images Ω
 - multiple ToFs \rightarrow a strong link over $\Omega \rightarrow$ a pattern



Patterns Mined from TV13 dataset

- Near Duplicates (ND)
 - easiest pattern to mine
 - many similar shots in TV series
- Objects/scenes
- Only a few is related with the 30 topics
- Some examples ...







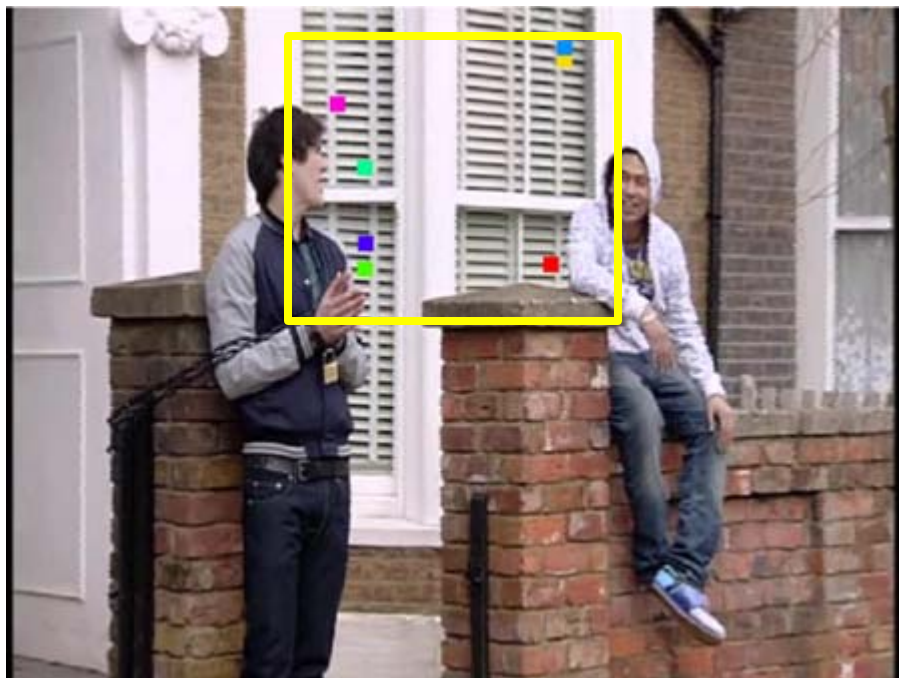






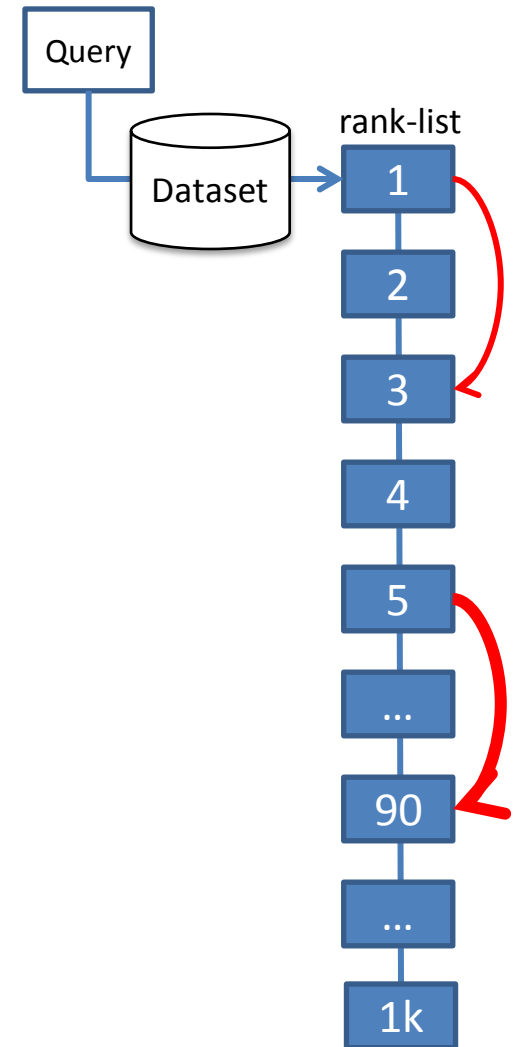






Approach-1: Frame-level linking

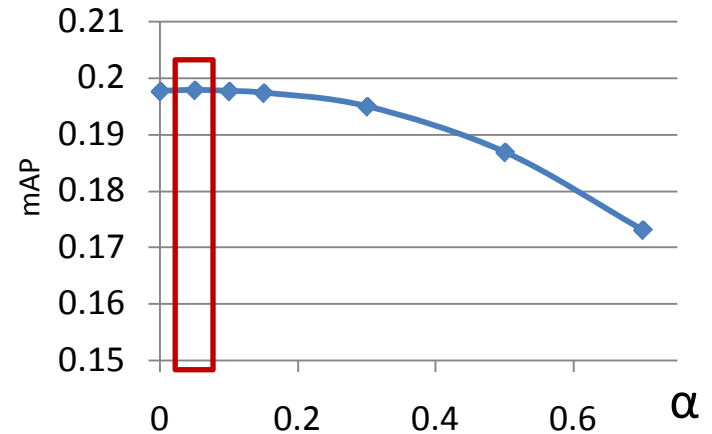
- Re-rank results using patterns
 - Random Walk
 - nodes: top 1k images in rank-list
 - initial weights: retrieval scores
 - link: mining results
 - link strength:
 - # patterns containing the image pair



Results – Frame-level Linking

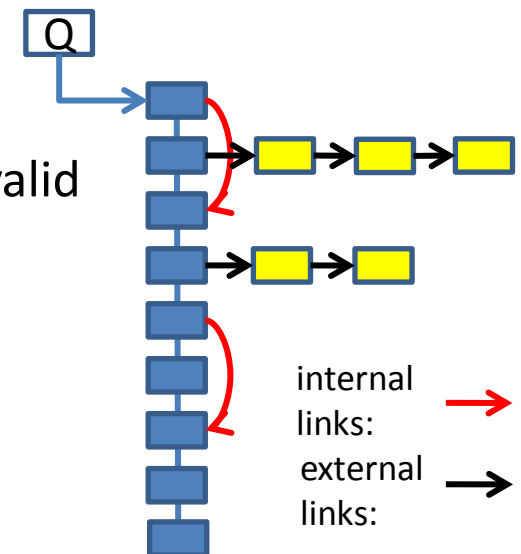
- Results

- weight for mining result : α
- weight for retrieval score : $1 - \alpha$
- best performance: $\alpha \approx 0$



- Problems

- only internal links are considered
- transitivity propagation at frame-level is not valid
- most links has nothing to do with the query
- emphasize Near Duplicates
 - NDs always have strong links



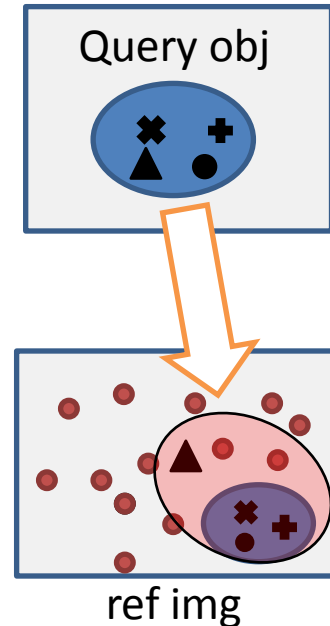
Approach-2: Instance-level linking

- Encode locations of matched points via (μ, σ^2)
 - μ : the centroid of matched points
 - σ^2 : the variance of the location
 - Z-test for region overlapping

- two sets of points overlap, if $Z = \frac{\mu_1 - \mu_2}{\sqrt{\sigma_1^2 + \sigma_2^2}} < t$

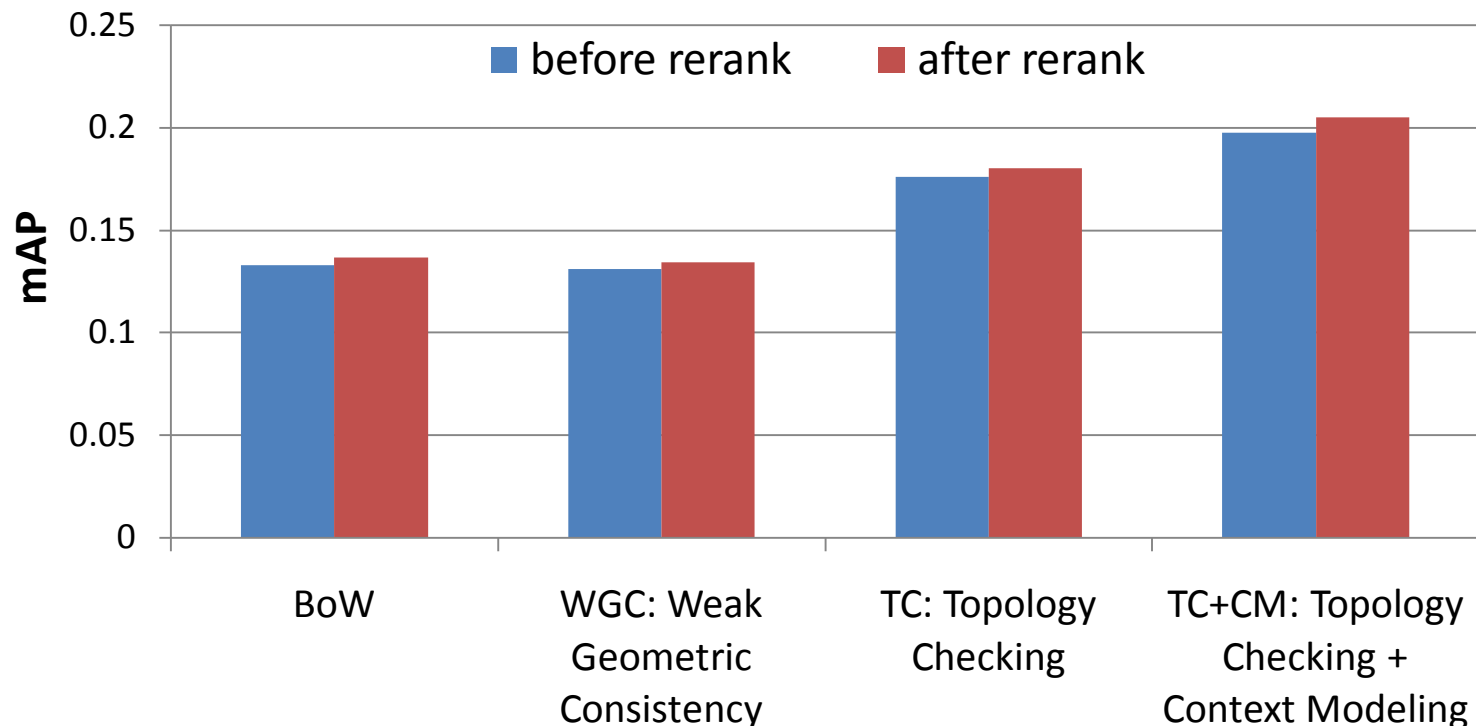
- Rank strategy

- no distinction on link strength (binary strength)
- give a bonus score to the linked images (both in/external links)



Results – Instance-level Linking

- Mining improves corresponding results consistently
 - invalid transitivity is prevented
 - only a few links are related with the 30 topics



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Conclusion

- Visual matching is mostly enough, despite low sampling rate
- Small objects are still difficult to search
- Complex spatial configuration in INS
 - Topology suits better
- ROI v.s. full-image search
 - tradeoff between precision and recall
 - generally, **full-image search** performs better, and
 - proper weighting is even better
- Pattern mining
 - many patterns can be linked offline
 - large fraction is near duplicates
 - low overlap with the query is the major problem